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Spring 3-30-1992

Fault Coverage Measurement Technique for Analog Circuits

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Recommended Citation

Ratazzi, E. Paul, "Fault Coverage Measurement Technique for Analog Circuits" (1992). Electrical Engineering and Computer Science. 227. [https://surface.syr.edu/eecs/227](https://surface.syr.edu/eecs/227?utm_source=surface.syr.edu%2Feecs%2F227&utm_medium=PDF&utm_campaign=PDFCoverPages)

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REPORT

on

Fault Coverage Measurement Technique for Analog Circuits

by

E. Paul Ratazzi

30 March 1992

The purpose of this report is to fulfill the Master's Project requirement for the M.S. (Electrical Engineering) degree (plan B, engineering investigation).

Faculty Advisor: Prof. Jia Approved: ____ _ Date Approved: __ _

SUMMARY

of **"Fault Coverage Measurement Technique for Analog Circuits"**

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The purpose of this report is to fulfill the Master's Project requirement for the M.S. (Electrical Engineering) degree (plan B, engineering investigation).

Measurement of a test sequence's fault coverage plays an important role in the specification of complex digital microcircuits. On the other hand, analog test engineers have not enjoyed the same benefit of being able to quantify how well a test sequence detects faults in an analog microcircuit. This fact of life is mainly due to the non-deterministic nature of analog signals. Other factors which have prohibited meaningful measurement of fault coverage in analog circuits include the effect of nominal component variations on circuit response and the widely-varied types of circuit functions that exist. In most cases the development of a thorough test set for even simple analog circuits is based on an ad-hoc collection of sometimes redundant tests. Test specifications are developed based on the circuit's function alone, without regard to the actual circuit architecture employed. With an increase in the complexity of analog circuits, and with the development of complex analog semicustom devices, it is becoming painfully apparent that there is a strong need to actually quantify fault coverage for analog circuits.

In an effort to define methods for performing fault simulation and measuring fault coverage in analog and mixed-mode circuits, techniques have been developed for defining a "fault dictionary" for a particular circuit, which accounts for the circuit's nominal component variations. This technique has been used by the author in an attempt to develop techniques for measuring the fault coverage that typical analog test methods provide for a particular analog device. A simplified operational amplifier test circuit model containing a transistor-level model of the device under test (DUT) is simulated and the output of the test circuit recorded in the fault dictionary. Faults are then singly inserted into the DUT and the data representing the unknown circuit condition is analyzed. Based on the fault dictionary, a statisticallybased "guess" is made as to whether the circuit is faulted or not. Consistently incorrect results indicate a fault that the test circuit does not propagate to the test circuit output. This fault is referred to as one which is not "covered" by the test sequence, i.e. the test sequence does not have fault detection coverage for this fault. Expanding this methodology to an entire test sequence for an entire fault set will yield a measure of fault detection coverage.

Faculty Advisor: Prof. Jia Approved: _____ _ Date Approved: ___ _

Abstract

This report describes an effort to develop a technique for measuring the amount of fault detection coverage that an analog test pattern has for a particular analog device. The technique is based on a software tool which statistically analyzes data from a circuit simulator. One example of a fault simulation experiment is presented, and some of the results are discussed. Finally, some ideas for future work in this area are given.

Contents

Introduction

Measurement of a test pattern's fault coverage plays an important role in the specification of complex digital microcircuits. Unfortunately, analog test engineers have not enjoyed the same benefit of being able to quantify how well a test pattern detects faults. This unfortunate fact can be attributed to the non-deterministic nature of analog signals and the inability to represent physical faults in a small number of fault classes (for example, stuck -at faults represent a large number of physical faults in digital logic circuits). Other factors which have prohibited meaningful measurement of fault coverage in analog circuits include the effect of nominal component variations on circuit response, the lack of mature analog simulators, and the wide variety of circuit functions that exist. In most cases, the development of a thorough test pattern for even simple analog circuits is based on an ad-hoc collection of sometimes redundant tests. Test specifications are developed based on the *circuit'sfunction,* without regard to the circuit's *architecture.* Increases in the complexity of analog microcircuits and the advent of analog application-specific integrated circuits (ASIC), are pointing to the need for being able to quantify test quality and develop test patterns which account for circuit topology.

Background

Fault analysis of analog circuits has been an active research area for many years. Literature surveys' show that the Department of Defense (DoD) has held a small but steady interest in this area since the beginning of the 1960s. Early efforts were designed to ease the task of isolating component failures on circuit cards containing analog circuitry. Later efforts had goals ranging from fault -driven automatic test pattern generation (ATPG) to built-in self test (BIST). The author's involvement in this area has been with more general goals in mind. First, to develop an understanding of the basic problems associated with the simulation of faults in analog circuits, and second, to investigate various methods of fault analysis. In May 1989, the U. S. Air Force's Rome Laboratory (RL) awarded an eighteen-month contract to David Sarnoff Research Center (DSRC) to research the state-of-the-art and develop a specific technique of analyzing analog circuit faults. The result is the methodology embodied by the Statistical Fault Analyzer (SFA).^{2,3}

SFA Basics

The SFA is a software tool which provides data analysis and circuit faulting capabilities to a circuit simulator such as SPICE 3Cl. It consists of a preprocessor which directs the simulation according to a set of control statements included in the simulator input file. These control statements describe how the circuit is to be faulted, the number of simulations to be run, and what information will form the output file. Gaussian component variations are specified by allowing any numerical value in the SPICE input (except node numbers) to be replaced by a mean and standard deviation value. The SFA also contains a post-processor to collect and format the output from the simulation. The SFA can post-process any numerical result of the simulation including nodal voltages, branch currents, frequency response, and transient data. The resulting files may be analyzed using two different statistical methods: hypothesis testing for fault detection and discrimination analysis for fault classification. For the purposes of this discussion, only hypothesis testing (fault detection) will be discussed.

Hypothesis Testing

For hypothesis testing, the SFA generates a data file containing simulation results for an unfaulted circuit. It usually contains many entries, each one slightly different due to component variations introduced through Monte Carlo methods. The data flle is a multivariate distribution representing the circuit's unfaulted behavior. This distribution forms the basis for the null hypothesis, H_0 , which states that the circuit is good or unfaulted. When simulation results from a faulted circuit are presented to the SFA, a hypothesis test is used to calculate the probability that the faulted response lies within the unfaulted distribution. If this probability is less than a predetermined threshold (confidence level), H_a is rejected and the fault is detected. Otherwise, H_o is incorrectly accepted, indicating that the fault may be undetectable. Incorrect acceptance of H_a is known as a Type II error and may be due to a truly undetectable fault or an ill-defined unfaulted distribution. Consistent rejection of H_0 , allowing for the expected number of Type II errors, indicates that the faulted circuit's response is distinguishable from the unfaulted circuit's response. When this is the case, the fault is detectable and the test that achieved the detection is said to "cover" the fault.4

Fault Detection Coverage

Fault detection coverage is a measure of a test method's ability to detect faults in the device under test (DUT). For analog circuits, a test method defines the forcing functions applied to the DUT and specifies the external test circuitry used. Analog fault detection coverage is dependent on the test pattern, the faults selected, and the test circuit. Thus, any measure of fault detection coverage for analog circuits must specify the entire test method, as well as the fault set used. Fault detection coverage is reported as a ratio of the number of detected faults to the total number of faults possible in the DUT. In the most general sense, the total number of faults possible would include combinations of individual faults, resulting in an astronomical number of circuit states. For simplicity, this investigation considers only "one-at-a-time," or singly-inserted faults.

Experiment Description

For this study, the hypothesis test routine contained in the SFA is used to determine if it is possible to measure the amount of fault detection coverage that specific analog test methods have for a given analog circuit. Before the actual experiment and results can be discussed, elements of the setup must be described. The elements used for this experiment include the DUT, the test circuit, and the fault set.

DUT Description

The DUT used in this experiment is a commercially available macrocell operational amplifier (MOPA). This macrocell is a part of the Raytheon Linear Array (RLA) series of analog ASICs. The selection of this device as a test case is based on two main factors. First, analog ASICs present an acute challenge with respect to developing quality tests. With standard single analog functions, it may be acceptable to have a function-driven, general-purpose test pattern that contains testing redundancies. However, when these functions are combined into large specialized circuits, as is the case with many analog ASICs, it is no longer acceptable to have an inefficient test pattern. Components of the test pattern must provide the most "bang for the buck" and be as independent as possible regarding the information

Figure 2. Test Circuit Containing D.U.T.

 $autt$ \bar{a} $36c$ e asu $\bar{\omega}$ \mathcal{C} h ω for i)Q (J \$:::

provided about the state of the circuit. At the same time, they must together give a complete and accurate evaluation of the DUT. In choosing the MOPA as the test case, it was recognized that in order to assess test quality for combinations of these functions, one must first master assessment of individual functions. The second reason for selecting this particular family of circuits is that they have a strong relevance to analog military microelectronics. The RLA family of devices is the first analog semi-custom parts to achieve qualification under the Joint Army-Navy (JAN) MIL-M-38510 specification system for microcircuits.⁵ This specification opens the door for widespread use of these devices in military systems. For this reason, it is in our best interest to seek better means of evaluating test quality for these devices. Figure 1 shows the MOPA internal architecture.

Test Circuit Description

In analog testing, the test circuit plays an extremely vital role in determining if faulty DUT behaviors are propagated to the measurement points. In fact, the test circuit is every bit as important to fault coverage as the test pattern is. For this reason, the test circuit must be grouped along with the DUT for any fault simulations. The test circuit selected for this investigation is a simplified operational amplifier test loop, such as those found on MIL-M-38510 analog detail specifications and in MIL-STD-883 analog test methods. The main point that distinguishes the DUT and the test circuit during simulation is that the DUT must be modeled structurally so that component faults can be inserted, whereas the test circuit may be modeled behaviorally or as a macro model since it is assumed that the test circuit contains no faults. Additionally, we assume that the test circuit is fixed and cannot be altered as a way of increasing fault coverage. However, note that alteration of the test circuit may very well be an excellent method of increasing fault coverage. A schematic of the test circuit containing the DUT appears in figure 2.

The schematic of figure 2 shows the DUT in a standard operational amplifier test circuit. Input patterns to this test circuit consist of applying a forcing voltage at V_s and opening or closing relays K1, K2, or K3. The output is measured at test point A. The tests that were implemented and their associated test patterns are shown in Table 1. Due to computational limitations, a full operational amplifier test suite was not applied, but will be in future investigations.

Table 1. Test Pattern Description.

Fault Set Selection

Selection of a realistic fault set for analog circuits (and perhaps for high-speed digital circuits) is a very difficult process. Very limited data is available on the types of faults which commonly occur in these circuits. For example, an Air Force study⁷ reports that 32% of IC failures are due to opens, 22% are due to shorts, and 18% are due to parametric or "soft" faults such as low gain. However, no breakdown is given for the type of structure or type of device (analog or digital) that the faults occurred in. Also, this data comes from field failures and may not be comparable to manufacturing defect data. In an attempt to remedy this situation, an effort⁸ is underway which is exploring the possibility of utilizing microcircuit defect simulators to generate a list of manufacturing faults prioritized by probability of occurrence. At the present time however, this approach is not well-defined and in this experiment the fault set selection was based solely on reasonable engineering judgement. For each transistor of the DUT, seven faults are considered. Each transistor lead (base, emitter, collector) can be shorted to each of the two remaining leads (3 faults), each lead can have a high resistance (3 faults), or the transistor's forward current gain $(\beta_{\rm r})$ can be low (1 fault). This makes a total of 91 faults possible throughout the circuit. Note that this fault set is not intended to represent the actual faults that can occur in this device. It is used only for proof-of-concept purposes until a more realistic fault set can be developed.

Simulation

Once the DUT, test circuit, and fault set have been defined and coded into the SFA input format, fault simulations may be run. For fault detection coverage analysis, which uses the basic hypothesis test, the circuit's nominal behavior must be defined. In this case, the unfaulted circuit is simulated a total of 100 times while introducing a 10% normal variation into each transistor's forward current gain (B_F) and Early voltage (V_A) . Previous sensitivity analyses¹ show that these two parameters have the most significant effect on transistor performance. The circuit is then simulated 100 times for each single fault condition. A hypothesis test is performed after each simulation. This procedure is iterated for each test condition considered. Results of the fault simulation indicate how many times H_0 was accepted or rejected for each fault and test condition.

Initial Results

Results to date have shown many examples of faults that are detected by one test pattern, and not another. For example, simulations (see appendix A for listings and summarized outputs) show that the offset voltage test $(V_{\alpha s})$ cannot distinguish between the nominal circuit and the circuit with a short inserted between the collector and base or collector and emitter of transistor Q5 (see figure 1). This is apparent from fault simulations where the V_{OS} test correctly accepts H_0 94% of the time when the circuit is nominal, yet incorrectly accepts H_{ρ} 92-95% of the time when the faults are present. On the other hand, the offset current (I_{0s}) test is able to detect these faults by causing the fault to propagate to the circuit output. I_{α} also correctly accepts H₀ during unfaulted runs, but rejects H₀ 100% of the time when the faults are inserted. One can conclude from this that the I_{os} test has fault detection coverage for these faults, while the $V_{\alpha s}$ test does not. Expanding this methodology to an entire test sequence for an entire fault set yields a measure of fault detection coverage or test quality.

Future Investigations

There are several areas which offer opportunities for additional investigation. First, focusing on refining the SFA methodology and researching practical methods of defining a fault set for a given circuit will increase the practicality of the SFA. Second, continued work on using the SFA tool to define techniques for measuring fault coverage, such as simulation of a full operational amplifier test suite will further reinforce the concept of analog fault coverage. Also, better means of generating practical analog fault sets would make the SFA much more useful. Eventually, it is hoped that these measurement techniques will be standardized in the same way that digital techniques have been in MIL-STD-883, Procedure 5012: "Fault Coverage Measurement for Digital Microcircuits."⁹

Conclusions

Initial results from an analog fault simulation experiment show that it is possible to measure the amount of fault detection coverage that a specific test method has for a given analog circuit. The method requires a transistor-level model of the DDT, a model of the test circuit, and a fault set in terms of component value or model parameter value modifications. Fault detection coverage is measured by taking the ratio of the number of faults detected by the hypothesis test to the total number of faults in the fault set. Additional work is needed in defining a realistic fault set and in extending the method to a complex analog ASIC containing many function modules.

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Appendix A

This appendix contains an SFA input file listing and two summary statistics output listings from the SFA.

Listing 1 shows the SFA input file used for this experiment. Comments are included to describe some of the SFA-specific syntax used. For a full description of the SFA control statements, see reference [2]. For a complete description of the SPICE 3C1 syntax, see the SPICE 3 users guide.

Listing 2 contains the summary output from the SFA run corresponding to the $V_{.}$ test. Note that the hypothesis test statistics indicate excellent results for the NOMINAL case, while very poor results are achieved for the Q5CBS (short between Q5's collector and base) case. This indicates that the $V_{\alpha s}$ does not posses fault detection coverage for this fault. Note that classification results are poor also.

Listing 3 is the summary output for the $I_{\alpha s}$ test. Note that these hypothesis test results are very good for both the NOMINAL case as well as the fault Q5CBS. This indicates that the I_{0s} test has fault detection coverage for this fault. It is also interesting to note that this test was able to correctly classify the fault 100% of the time. However, one should be cautious not to conclude from the good classification result that I_{os} has fault *location* coverage for Q5CBS. When other faults are considered, the detection (hypothesis test) results may remain high, but misclassification *between faults* would most likely increase.

OP AMP TEST LOOP FOR DC PARAMETER MEASUREMENT OF MOPAl * *START OF FAULT ANALYZER CONTROL SECTION. THE *FOLLOWING COMMENTS DESCRIBE THE DIFFERENT TYPE *OF SFA CONTROL STATEMENTS THAT ARE USED . * * * * tGOOD <number_of_runs> DIRECTS THE SFA TO SIMULATE THE CIRCUIT WITH NO FAULTS FOR THE NUMBER OF TIMES SPECIFIED. NOMINAL COMPONENT VARIATIONS * ARE INTRODUCED USING MONTE CARLO * TECHNIQUES . * * * #<component_narne> <faulted_value> <number_of_runs> <fault name> [<model_parameter>] * DIRECTS THE SFA TO FAULT THE COMPONENT * NAMED BY REPLACING THE UNFAULTED VALUE WITH THE GIVEN FAULTED VALUE. THE RESULTING FAULTY CIRCUIT IS SIMULATED FOR THE NUMBER OF TIMES SPECIFIED. NOMINAL COMPONENT VARIATIONS ARE INTRODUCED INTO OTHER UNFAULTED COMPONENTS. IF THE FAULTED VALUE CORRESPONDS TO A MODEL PARAMETER WITHIN A DEVICE MODEL, THE NAME OF THE MODEL PARAMETER SHOULD BE GIVEN. %dc <node_value> [<node_value> <node_value> ...] CAUSES THE SFA TO USE THE DC NODE VALUES SPECIFIED FOR FAULT ANALYSIS. MUST SPECIFY . OP IN INPUT FILE. %ac <node_value> [<node_value> <node_value> ...] CAUSES THE SFA TO USE VECTORS FROM AN AC ANALYSIS FOR FAULT ANALYSIS. MUST SPECIFY .AC IN INPUT FILE. %polar CAUSES THE SFA TO STORE RESULTS IN POLAR NOTATION. THE DEFAULT IS RECTANGULAR FORM.

[~]^N

*

ANY NUMERICAL VALUE EXCEPT NODE NUMBERS MAY BE * GIVEN A STATISTICAL VALUE BY REPLACING THE * VALUE WITH [<mean>,<standard_deviation>]. THE ACTUAL * VALUE USED DURING SIMULATION WILL THEN BE CALCULATED USING MONTE CARLO METHODS FOR EACH * GOOD AND FAULTED SIMULATION. *
#GOOD 100 * tRQlCB 1.0 100 QlCBS #RQlCE 1.0 100 QlCES #RQlBE 1.0 100 QlBES #QPNPSl l.OE8 100 QlCO RC #QPNPSl l.OE8 100 QlBO RB #QPNPSl l.OE8 100 QlEO RE #QPNPSl 1.0 100 QlLOWB BF * #RQ2CB 1.0 100 Q2CBS #RQ2CE 1.0 100 Q2CES #RQ2BE 1.0 100 Q2BES #QPNPS2 l.OE8 100 Q2CO RC #QPNPS2 l.OE8 100 Q2BO RB #QPNPS2 l.OE8 100 Q2EO RE #QPNPS2 1.0 100 Q2LOWB BF * #RQ3CB 1.0 100 Q3CBS #RQ3CE 1.0 100 Q3CES #RQ3BE 1.0 100 Q3BES #QPNPS3 l.OE8 100 Q3CO RC #QPNPS3 l.OE8 100 Q3BO RB #QPNPS3 l.OE8 100 Q3EO RE #QPNPS3 1.0 100 Q3LOWB BF * #RQ4CB 1.0 100 Q4CBS #RQ4CE 1.0 100 Q4CES #RQ4BE 1. 0 100 Q4BES #QNPNS4 l.OE8 100 Q4CO RC #QNPNS4 l.OE8 100 Q4BO RB #QNPNS4 l.OE8 100 Q4EO RE #QNPNS4 1.0 100 Q4LOWB BF

Listing 1. SFA Input File (continued).

Listing 1. SFA Input File (continued).

Listing 1. SPA Input File (continued).

*

Listing 1. SPA Input File (continued).

#QNPNS6 1.0EB 100 Q6EO RE #ONPNS6 1.0 100 O6LOWB BF * #RQ7CB 1.0 100 Q7CBS #RQ7CE 1.0 100 Q7CES #RQ7BE 1.0 100 Q7BES #QMPIS7 1 . 0EB 100 Q7CO RC #QMPIS7 1.0EB 100 Q7BO RB tQMPIS7 1 . 0EB 100 Q7EO RE iQMPIS7 1.0 100 Q7LOWB BF *
#RQ8CB 1.0 100 Q8CBS #RQ8CE 1.0 100 Q8CES #RQ8BE 1.0 100 Q8BES iQNPNSB 1.0EB 100 QBCO RC #QNPNSB 1.0EB 100 QBBO RB #ONPNS8 1.0E8 100 O8EO RE #QNPNSB 1 . 0 100 QBLOWB BF *
#RQ9CB 1.0 100 Q9CBS tRQ9CE 1 . 0 100 Q9CES iRQ9BE 1 . 0 100 Q9BES iQNPNS9 1.0EB 100 Q9CO RC #ONPNS9 1.0E8 100 Q9BO RB #ONPNS9 1.0E8 100 O9EO RE #ONPNS9 1.0 100 Q9LOWB BF * iRQ13CB 1 . 0 100 Q13CBS

> I *w*

*
#RQ6CB 1.0 100 Q6CBS iRQ6CE 1.0 100 Q6CES tRQ6BE 1 . 0 100 Q6BES iQNPNS6 1 . 0EB 100 Q6CO RC #QNPNS6 1.0E8 100 Q6BO RB

tRQSCB 1.0 100 QSCBS #RO5CE 1.0 100 O5CES tRQSBE 1.0 100 QSBES tQNPNSS 1.0EB 100 QSCO RC tQNPNSS 1 . 0EB 100 QSBO RB #ONPNS5 1.0E8 100 Q5EO RE #ONPNS5 1.0 100 O5LOWB BF

tRQ13CE 1 . 0 100 Q13CES iRQ13BE 1.0 100 Q13BES #QNPNS13 1.0E8 100 Q13CO RC #ONPNS13 1.0E8 100 Q13BO RB #ONPNS13 1.0E8 100 O13EO RE #ONPNS13 1.0 100 Q13LOWB BF *
#RQ14CB 1.0 100 Q14CBS #RQ14CE 1.0 100 Q14CES #RQ14BE 1.0 100 Q14BES #QNPNS14 1.0E8 100 Q14CO RC iQNPNS14 1.0EB 100 Q14BO RB #ONPNS14 1.0E8 100 O14EO RE #ONPNS14 1.0 100 Q14LOWB BF * #RQ15CB 1.0 100 Q15CBS iRQ15CE 1.0 100 Q15CES #RQ15BE 1 . 0 100 Q15BES #QPNPS15 1.0EB 100 Q15CO RC #QPNPS15 1 . 0EB 100 Q15BO RB #QPNPS15 1.0EB 100 Q15EO RE #QPNPS15 1.0 100 Q15LOWB BF *
#RQ17CB 1.0 100 Q17CBS #RQ17CE 1.0 100 Q17CES #RQ17BE 1.0 100 Q17BES #QPNPS17 1.0EB 100 Q17CO RC #QPNPS17 1.0EB 100 Q17BO RB iQPNPS17 1.0EB 100 Q17EO RE iQPNPS17 1.0 100 Q17LOWB BF *
#RC1S 1.0 100 C1S * *NODE 9 CORRESPONDS TO THE TEST LOOP OUTPUT POINT . *SEE FIGURE 2, TEST POINT A. $8dc₉$ * *END OF SFA CONTROL SECTION . * *START OF TEST CIRCUIT.

*OPERATING POINT ANALYSIS GIVES US DC VALUES AT ALL *NODES. .OP * *SUPPLY VOLTAGES (VSP, VSN) AND BIAS CURRENT (ISET) . VSP 10 0 DC +15V VSN 11 0 DC -15V ISET 10 5 +lOUA * *LOOP CONTROL VOLTAGE (VS). SEE TABLE 1 FOR VS *SETTINGS . vs 8 0 ov * *ENULL IS THE NULLING AMPLIFIER. IT IS MODELED HERE *AS AN SEMI- IDEAL AMPLIFIER WITH OPEN LOOP GAIN OF *1,800,000. ENULL 9 0 7 0 -1.8E6 * *XDUT IS THE SUBCIRCUIT CALL TO OUR DEVICE UNDER *TEST . XDUT 4 3 11 6 10 5 MOPAlTX * *FOR Kl OPEN, SET RS2=100 KOHMS . FOR Kl CLOSED, SET *RS2=0.01 OHMS. FOR K2 OPEN SET RSl=lOO KOHMS. FOR *K2 CLOSED, SET RSl=O.Ol OHMS. SEE FIGURE 2 AND *TABLE 1 FOR Kl AND K2 SETTINGS. RSl 1 3 0.01 RS2 2 4 0.01 * *Rl, R2, R3, R4, Cl, AND RF ARE FIXED-VALUE COMPONENTS *OF THE TEST CIRCUIT. Rl 1 0 100 R2 2 0 100 R3 6 7 lOOK R4 8 7 lOOK Cl 9 7 O.lUF RF 9 2 49.9K * *LOAD RESISTOR (RL) . FOR K3 OPEN, COMMENT OUT RL. FOR *K3 CLOSED, LEAVE RL IN. SEE FIGURE 2 AND TABLE 1 FOR *K3 SETTINGS.

*RL 6 0 lOK * *START OF OUT SUBCIRCUIT. . SUBCKT MOPAlTX 1 2 3 4 5 6 * (+) (-) -VS VO +VS ISET Ql 9 7 5 3 QPNPSl 0.2X RQlCB 9 7 [l.OE8,0.0] RQlCE 9 5 [l.OE8,0.0] RQlBE 7 5 [l . OE8,0.0] Q2 11 2 9 3 QPNPS2 RQ2CB 11 2 [l.OE8,0.0] RQ2CE 11 9 [l.OE8,0.0] RQ2BE 2 9 [l.OE8,0.0] Q3 12 1 9 3 QPNPS3 RQ3CB 12 1 [l.OE8,0.0] RQ3CE 12 9 [l.OE8,0.0] RQ3BE 1 9 [l .OE8,0 . 0] Q4 11 11 3 3 QNPNS4 RQ4CB 11 11 [l.OE8,0.0] RQ4CE 11 3 [l.OE8,0 . 0] RQ4BE 11 3 [l.OE8,0.0] Q5 12 11 3 3 QNPNS5 RQ5CB 12 11 [l.OE8,0.0] RQ5CE 12 3 [l.OE8,0.0] RQ5BE 11 3 [l.OE8,0.0] Q6 13 12 3 3 QNPNS6 RQ6CB 13 12 [l.OE8,0.0] RQ6CE 13 12 [l.OE8,0.0] RQ6BE 12 3 [l .OE8,0.0] Q7 3 13 4 3 QMPIS7 RQ7CB 3 13 [l.OE8,0.0] RQ7CE 3 4 [l.OE8,0.0] RQ7BE 13 4 [l.OE8,0.0] Q8 5 13 4 3 QNPNS8 RQ8CB 5 13 [l.OE8,0.0] RQ8CE 5 4 [l.OE8,0.0] RQ8BE 13 4 [l.OE8,0 . 0] Q9 4 12 3 3 QNPNS9 RQ9CB 4 12 [l . OE8,0.0] RQ9CE 4 3 [l.OE8,0.0] RQ9BE 12 3 [l.OE8,0.0]

Listing 1. SFA Input File (continued).

Listing 1. SFA Input File (continued).

 $A-4$

+ XTB=1.7 NE=1.4 BR=19 VAR=9.0 IKR=3.57E-4 ISC=1.0E-16 NC=1. 2 RB=[161.0,0.0) + RE= [1.9,0.0) RC=[235.0,0.0) CJE=5.52E- 13 VJE=0.75 MJE=0.34 CJC=2.89E-13 VJC=0.6 + MJC=0.42 CJS=1.39E-12 VJS=0.47 MJS=0.32 XCJC=O.S TF=2.0E-10 TR=S.OE-9) * .MODEL QNPNS14 NPN (IS=5.2E-16 BF=[250 . 0,25 . 0) VAF=[130.0,13.0) IKF=1.44E-2 ISE=1. 61E-16 + XTB=1.7 NE=1.4 BR=19 VAR=9.0 IKR=3.57E-4 ISC=1.0E-16 NC=1.2 RB=[161.0,0.0) + RE=[1.9,0.0) RC=[235.0,0 . 0) CJE=5.52E-13 VJE=0.75 MJE=0.34 CJC=2.89E-13 VJC=0.6 + MJC=0.42 CJS=1.39E-12 VJS=0.47 MJS=0.32 XCJC=O.S TF=2.0E-10 TR=S.OE-9) * .MODEL QPNPS1 PNP (IS=6.3E-16 BF=[155.0,15.5) VAF=[60.0,6.0) IKF=1.0E-4 ISE=1.25E-15 + XTB=0.55 NE=1.5 BR=27 VAR=18.6 IKR=3.0E-5 ISC=4.74E-16 NC=1.2 RB=[540.0,0.0) + RE=[45.0,0.0) RC=[575.0,0.0) CJE=1.7E-13 VJE=0.41 MJE=0.16 \uparrow CJC=6.8E-13 VJC=0.54
 \uparrow + MJC=0.37 TF=3.5E-8 ~ + MJC=0.37 TF=3.5E-8 PTF=20 TR=7.0E-7) * .MODEL QPNPS15 PNP (IS=6.3E-16 BF=[155.0,15.5) VAF=[60.0,6.0) IKF=1.0E-4 ISE=1.25E-15 + XTB=0.55 NE=1.5 BR=27 VAR=18.6 IKR=3.0E-5 ISC=4.74E-16 NC=1.2 RB=[540.0,0.0) + RE=[45.0,0.0) RC=[575.0,0.0) CJE=1.7E-13 VJE=0 . 41 MJE=0.16 CJC=6.8E-13 VJC=0.54 + MJC=0.37 TF=3.5E-8 PTF=20 TR=7.0E- 7) * .MODEL QPNPS17 PNP (IS=6.3E-16 BF=[155.0,15.5) VAF=[60.0,6.0) IKF=1.0E-4 ISE=1.25E- 15 + XTB=0.55 NE=1.5 BR=27 VAR=18.6 IKR=3.0E-5 ISC=4.74E-16 NC=1.2 RB=[540.0,0.0) + RE=[45.0,0.0) RC=[575.0,0.0) CJE=l.7E-13 VJE=0.41 MJE=0.16 CJC=6.8E-13 VJC=0.54 + MJC=0.37 TF=3.5E-8 PTF=20 TR=7.0E-7) *

.MODEL QMPIS7 PNP (IS=1.38E-15 BF=[250.0,25.0) VAF=[100.0,10.0) IKF=2.56E-4 ISE=4.08E-15 + XTB=0.55 NE=1.7 BR=0.22 VAR=19 IKR=1.82E-6 ISC=5.21E-14 RB=[100.0,0.0) + RE=[SO.O,O.O] RC=[122.0,0.0) CJE=1.79E-13 VJE=0.41 MJE=0.22 CJC=2.39E-12 + VJC=0.48 MJC=0.32 TF=1.0E-8 TR=9.5E-8 NC=1.14) * .ENDS MOPA1TX *END OF DUT SUBCIRCUIT * .END

*END OF TEST CIRCUIT

Listing 1. SFA Input File (continued).

Listing 1. SFA Input File (continued).

Listing 2. Summary Output for V_{os} Test.

 $A - 7$

Listing 3. Summary Output for I_{OS} Test.

